

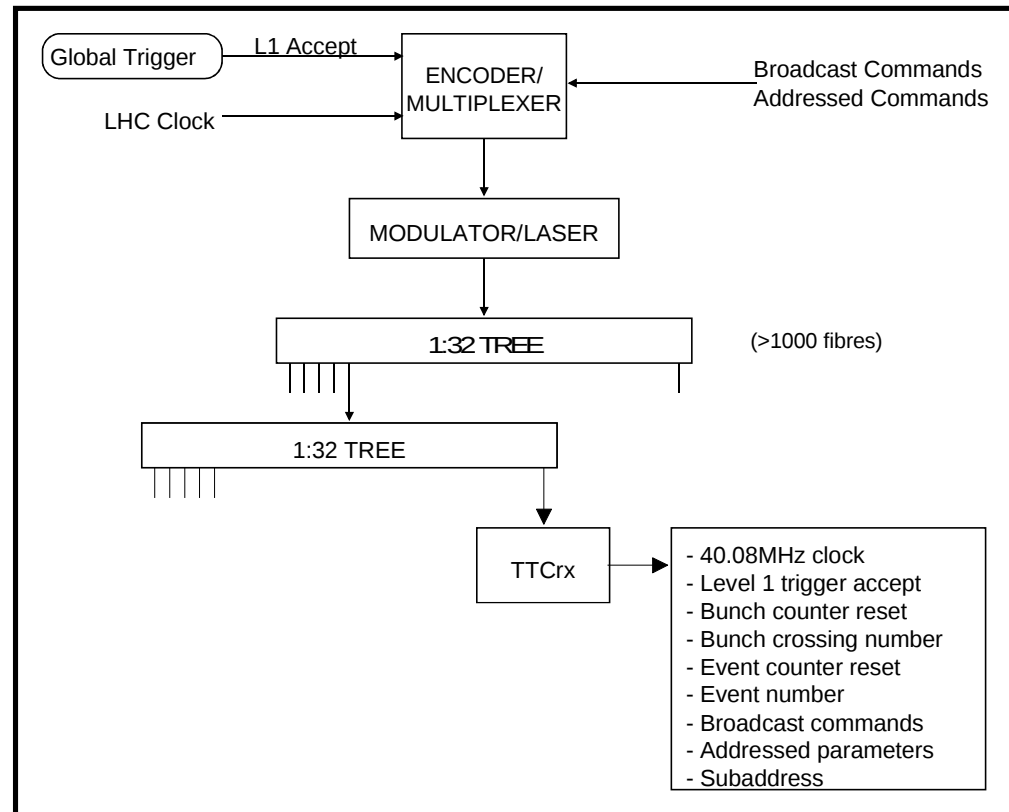
Practical Examples from HEP

- The TTC system
 - The system
 - Data format
 - Line coding
 - TTCrx: Architecture
 - Limiting amplifier
 - Clock recovery
 - Jitter measurements
- The CMS tracker analogue data link
 - The CMS tracker data path
 - The linear laser-driver
 - Optical link prototype

The TTC system

Timing Trigger and Control distribution system:

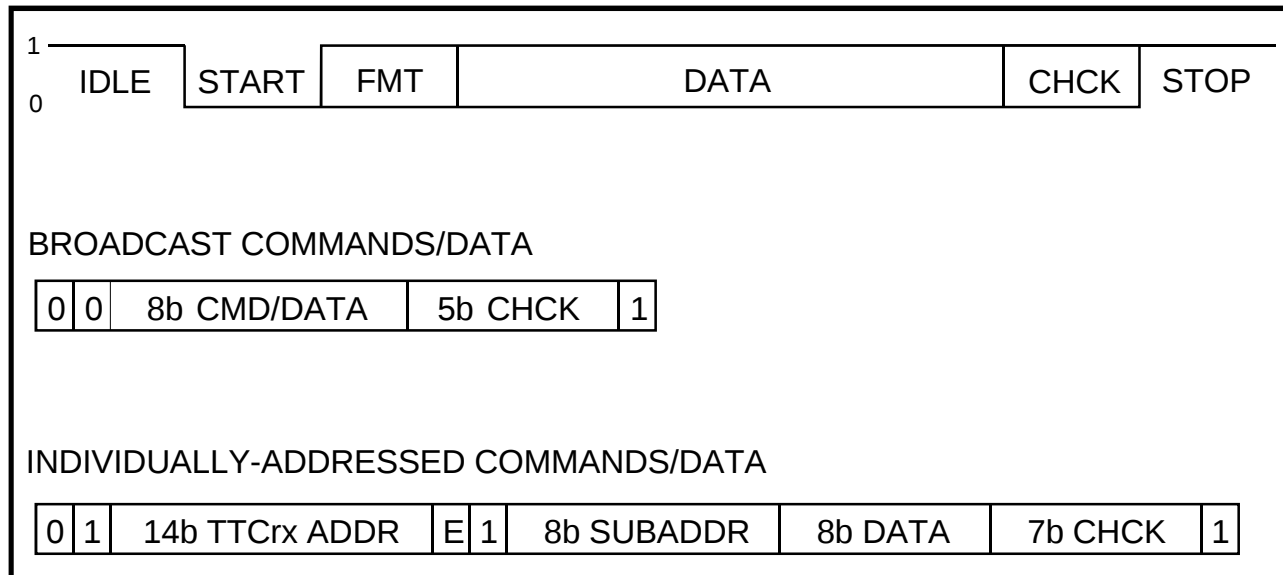
- Broadcast system:
 - Single laser source
 $\lambda=1300\text{nm}$
 - Up to 1024 destinations
 - Data rate 80Mbit/s
- Point-to-point span: 100m
- Uses time division multiplexing to transmit two channels simultaneously
 - Trigger channel: low latency
 - Data channel:
 - Broadcast commands
 - Addressed data
- Main objective:
 - Detector synchronization



The TTC system

Data format:

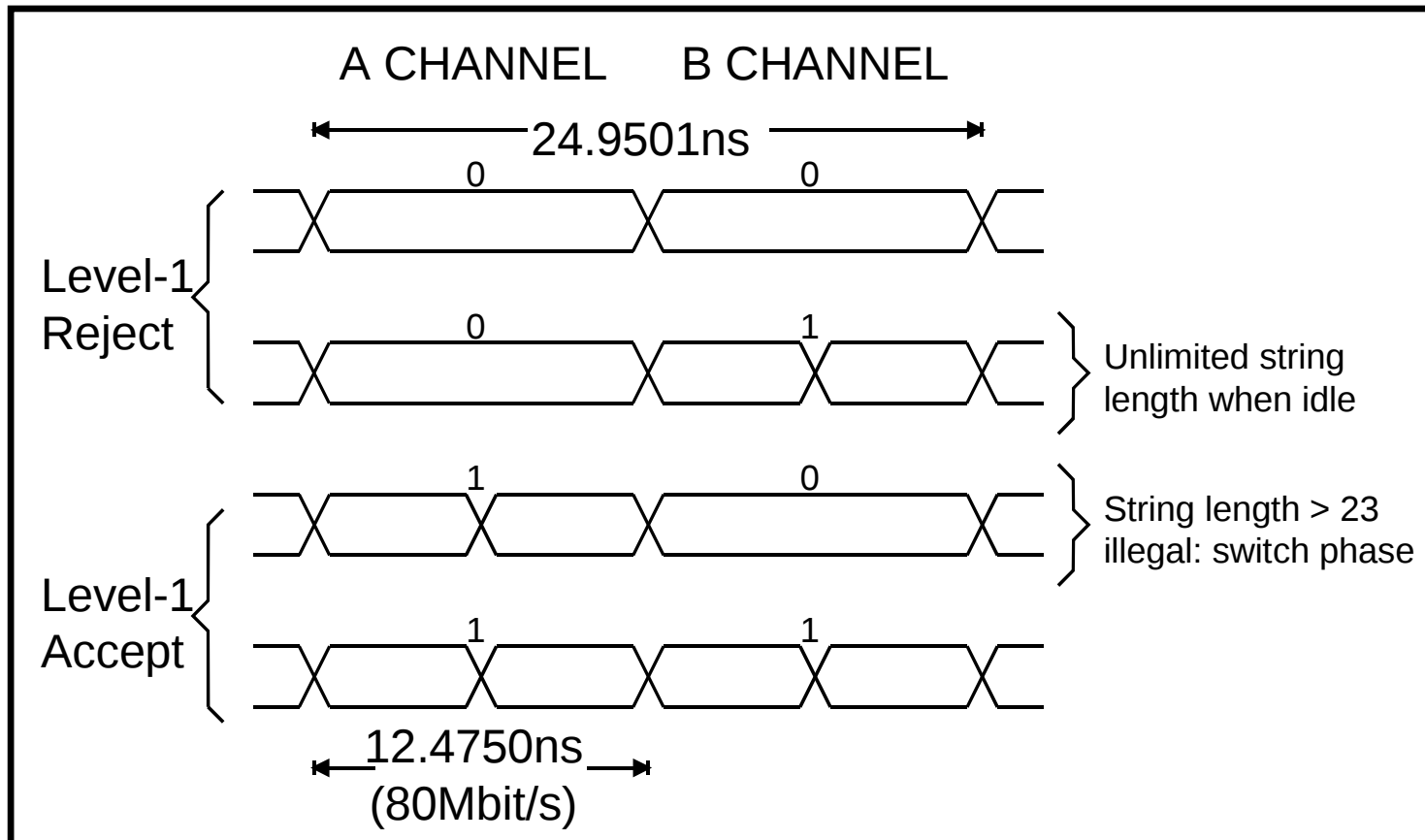
- Trigger channel:
 - single bit yes/no decision per cycle (40MHz)
 - minimum latency
- Data channel:
 - Addressed data: 42-bit frame (maximum latency)
 - Broadcast commands: 16-bit frame (reduced latency)
 - Hamming code: detection of double bit errors and correction of single bit errors
 - Idle sequence: stream of “1”



The TTC system

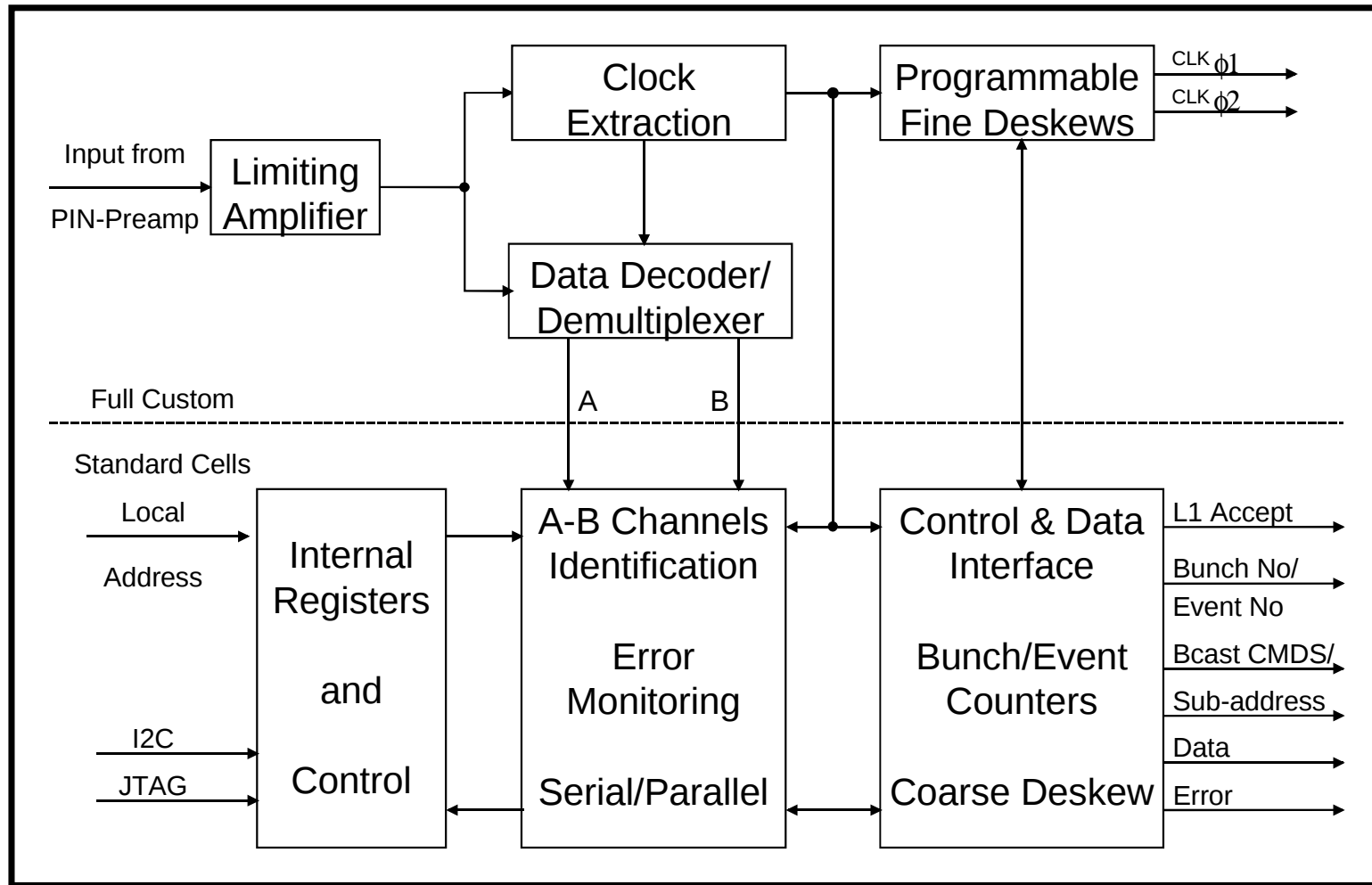
Line coding:

- BiPhase Mark code: very low DC unbalance



The TTC system

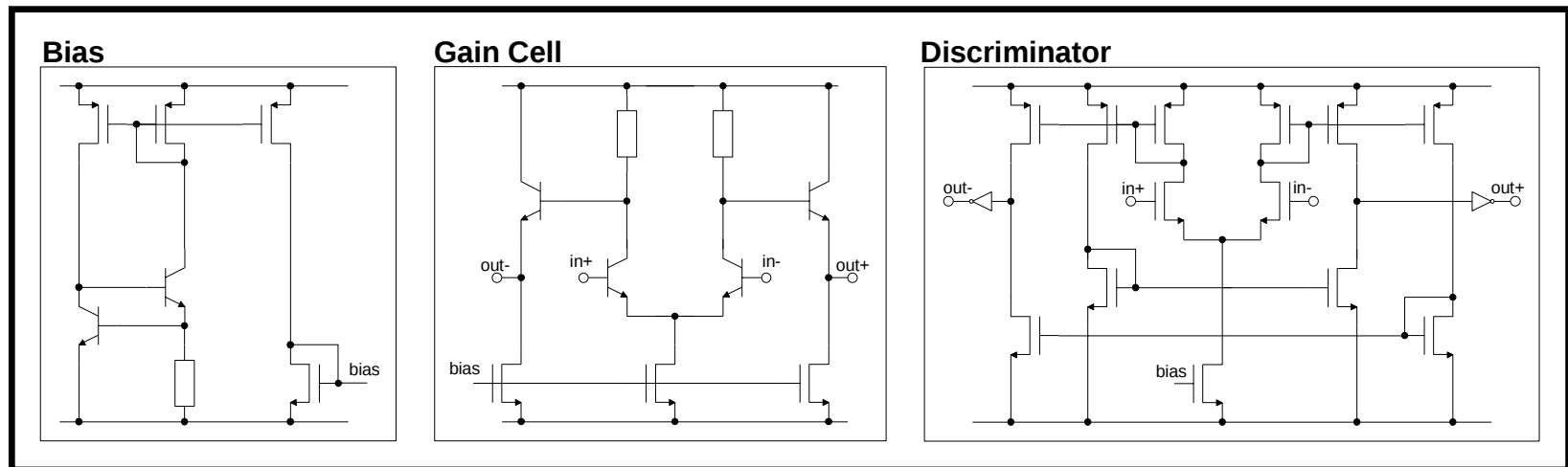
TTCrx: Architecture



The TTC system

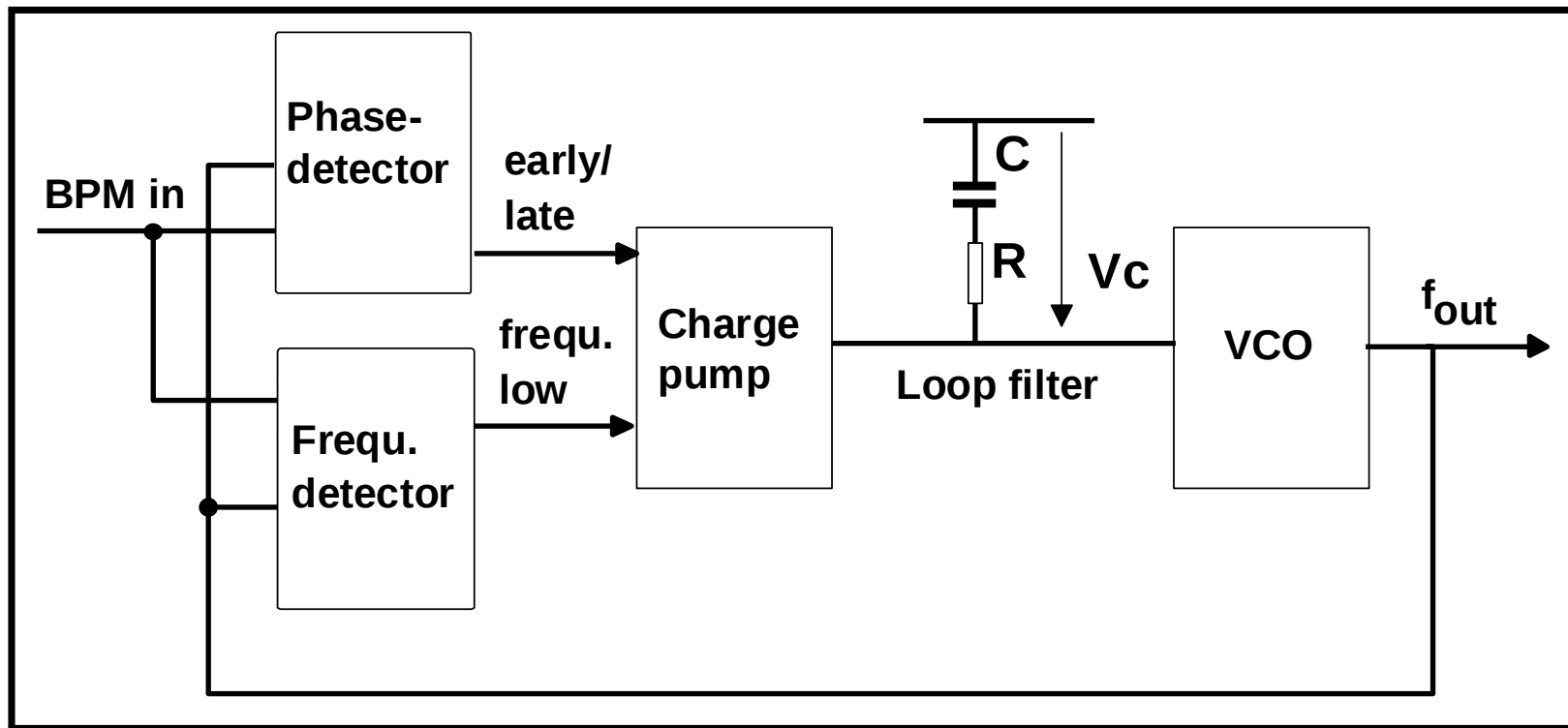
Limiting Amplifier:

- Fully differential:
 - Cascade of four identical gain cells
 - + Transconductance amplifier
- High-Gain bandwidth product:
 - Gain: 99dB
 - Bandwidth: 100MHz
- Implemented in radiation hard technology



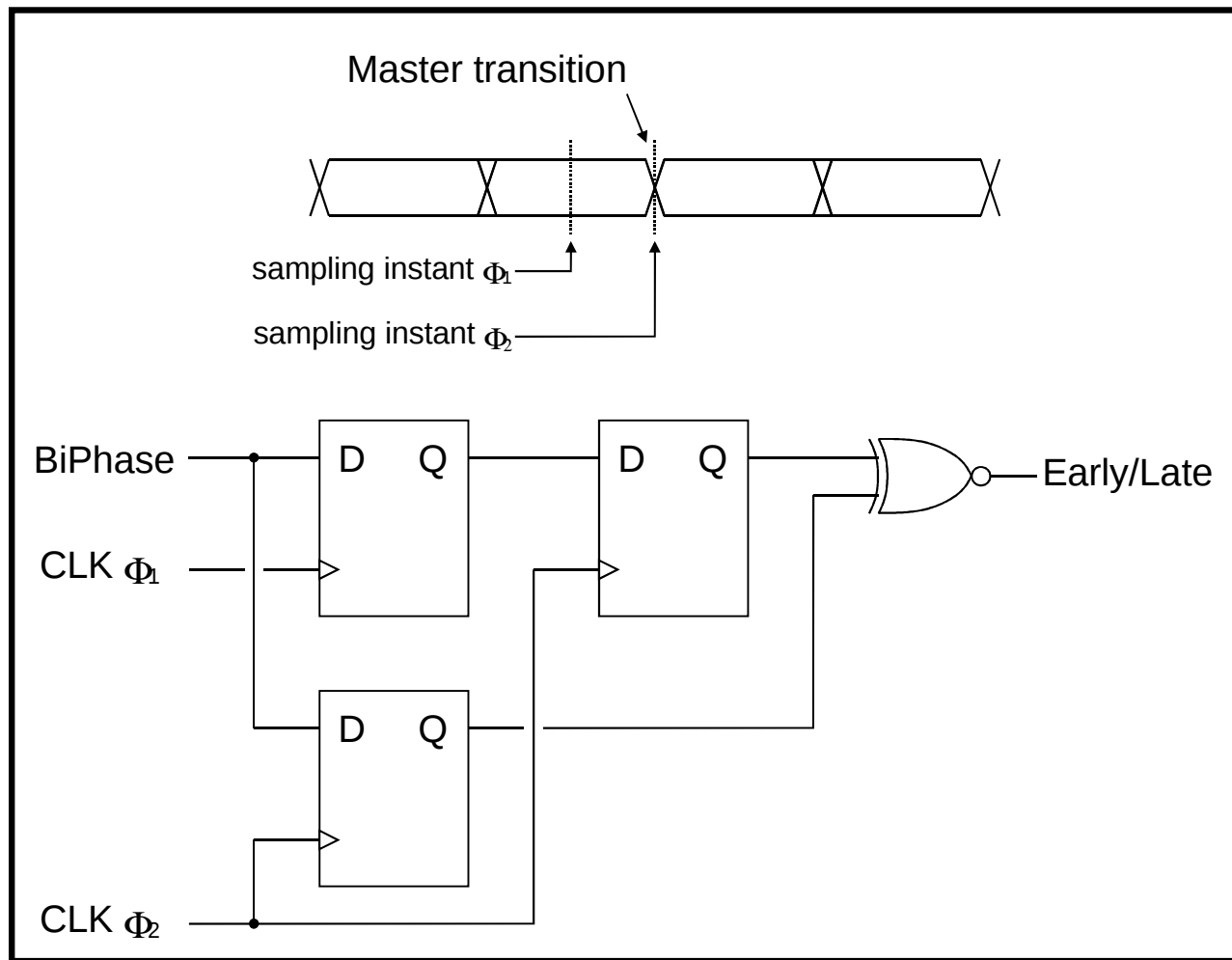
The TTC system

Clock recovery: PLL



The TTC system

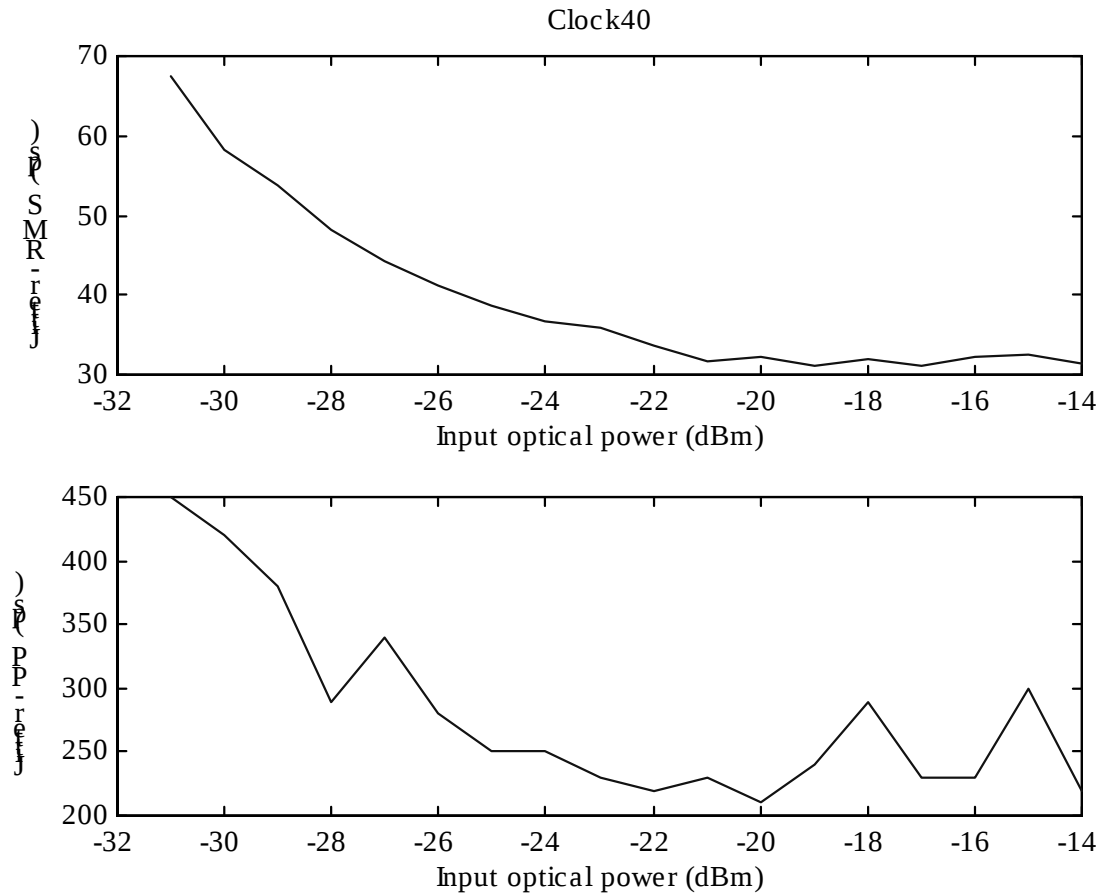
Clock recovery: Phase Detector



The TTC system

Jitter measurements:

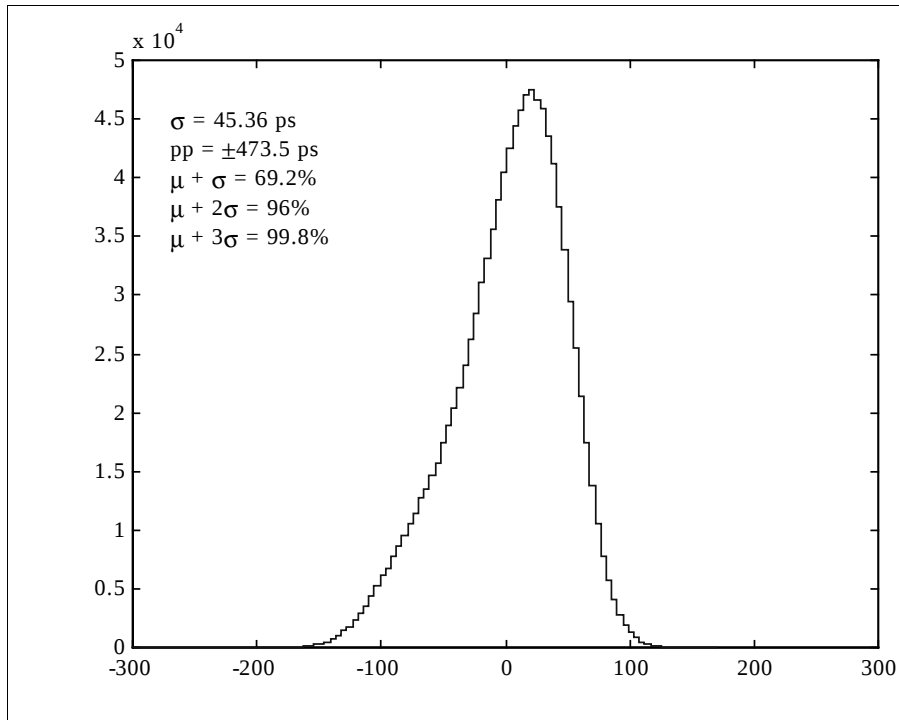
- Jitter versus optical power



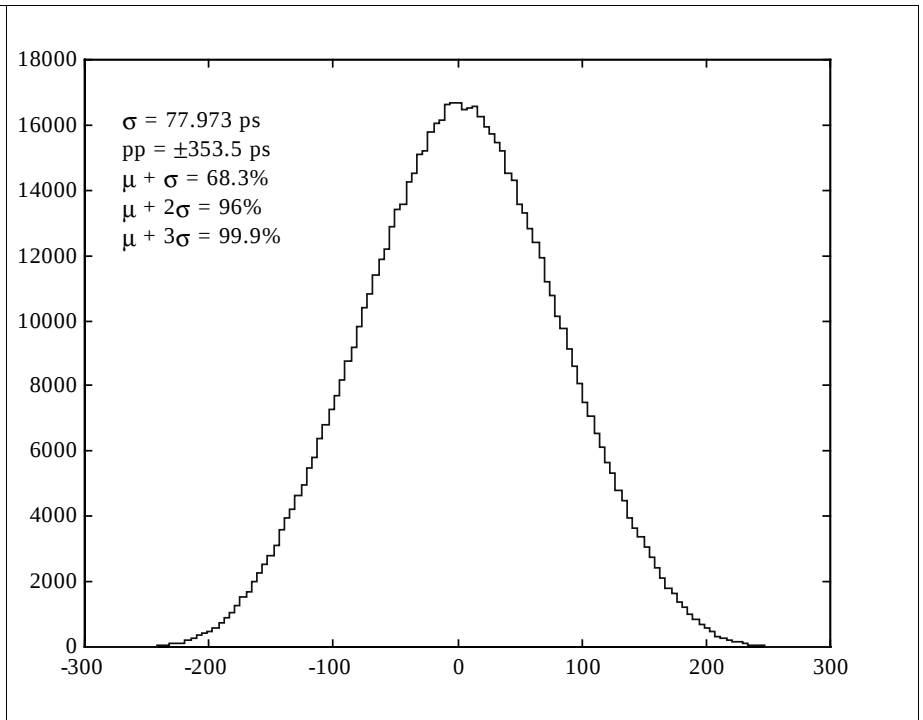
The TTC system

Jitter measurements:

TTCrx vs Reference (13h:48min)

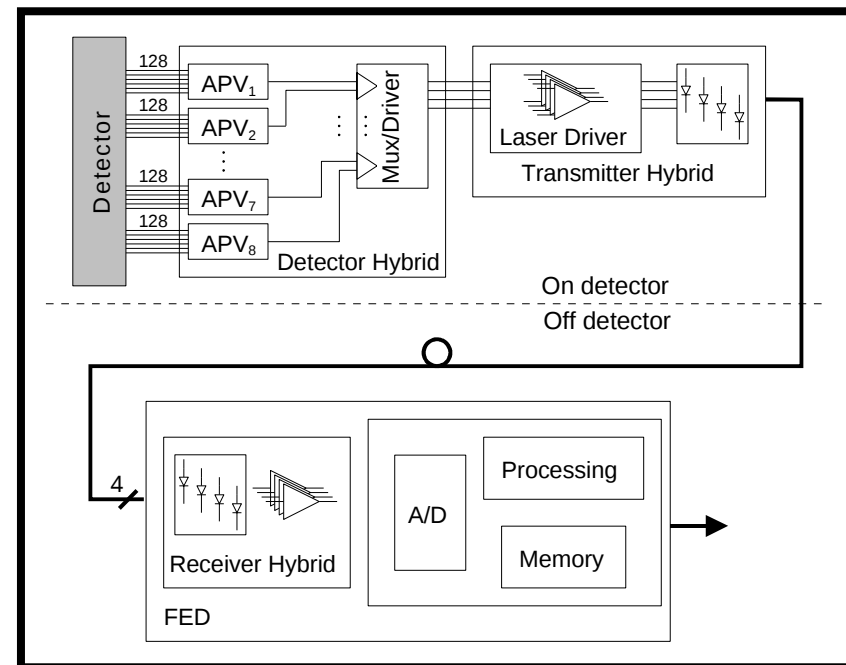


TTCrx vs TTCrx (9h:14min)



The CMS tracker data path

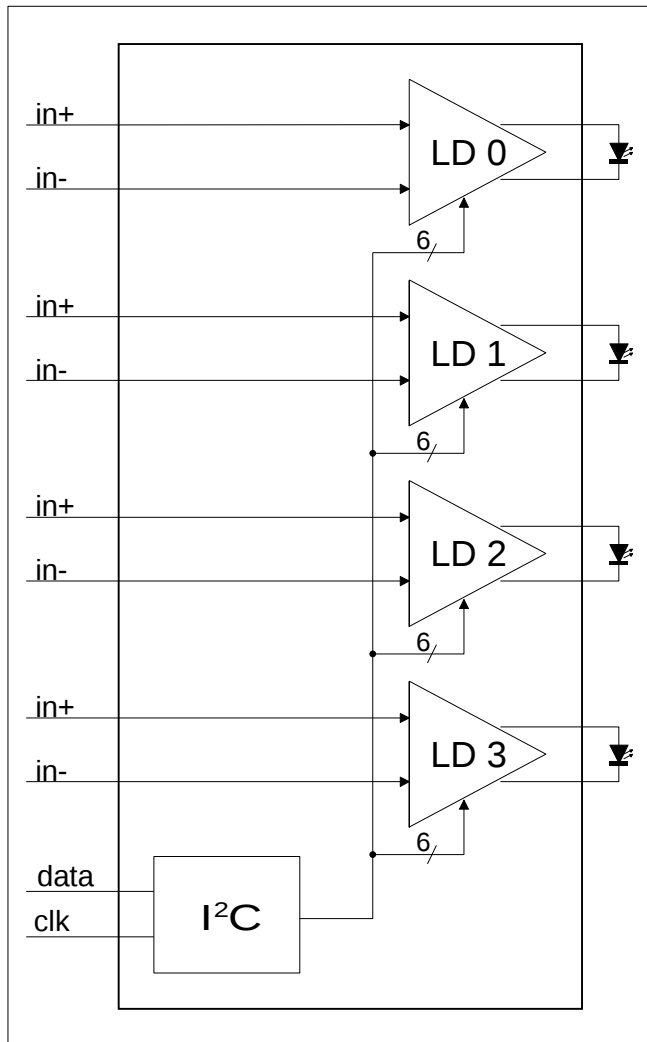
- CMS tracker detector:
 - Silicon microstrips
 - Microstrips gas chambers
- 128 Detector-Channels per APV
- Data from 2 APVs Multiplexed
 - 40Ms/s Communication
- Electrical-to-optical conversion
 - Direct amplitude modulation
analogue optical transmission
- 1M detector channels
 - 50K optical read-out links
- Major system requirements:
 - Radiation hardness
 - Length: < 120m
 - Peak SNR: 48dB
 - Non-linearity: < 2.5%
 - Settling time to 1%: < 18ns



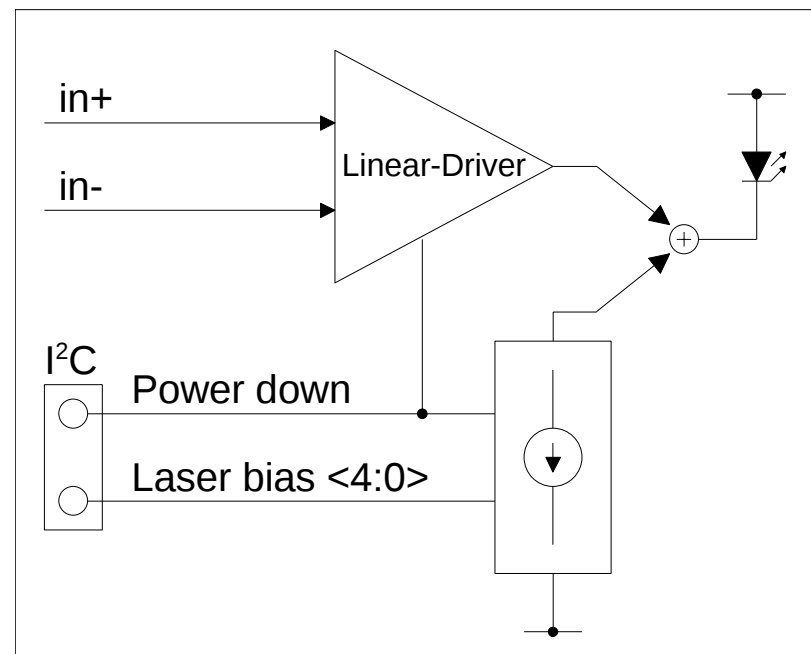
The linear laser-driver

- Major requirements:
 - Radiation hard technology
 - Currently: prototype in 0.8 μ m standard BiCMOS
 - Four channels per IC
 - Dynamic range: 8 bits
 - Integral nonlinearity: < 1%
 - Equivalent input noise: < 1mV
 - Settling time: < 10ns to within 1% of the final value
 - Crosstalk: < 0.3%

The linear laser-driver

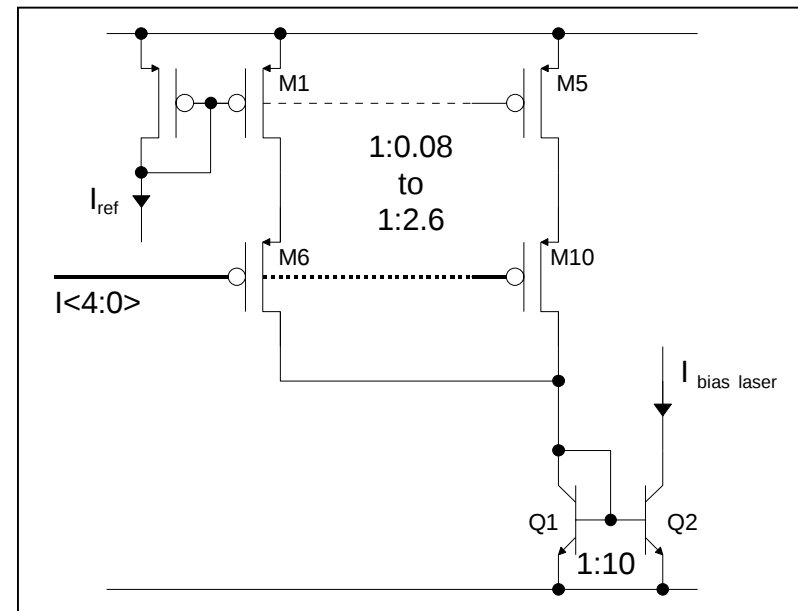
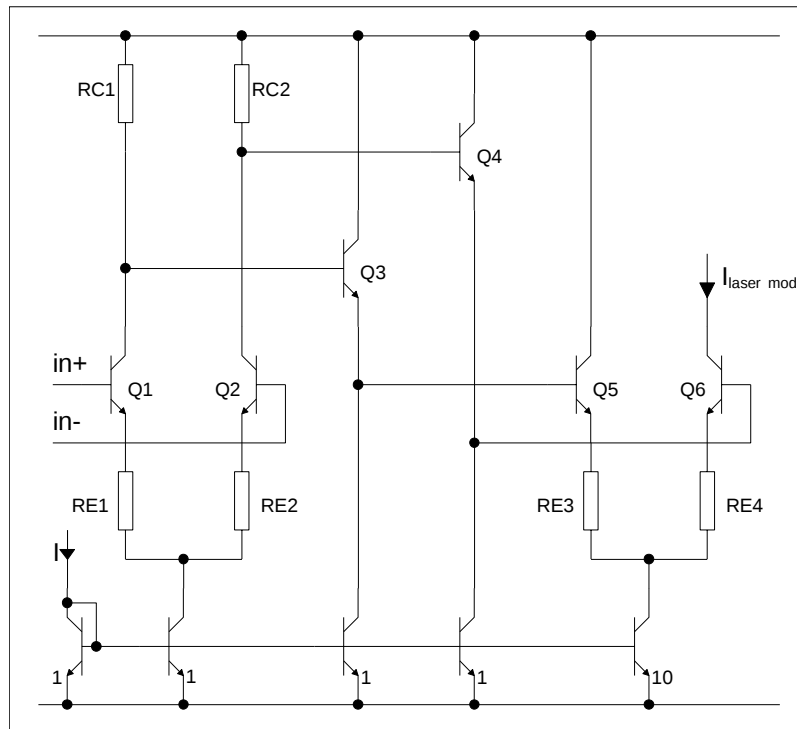


- Four linear drivers per IC
- Programmable laser bias
- I²C interface
- Per channel power-down



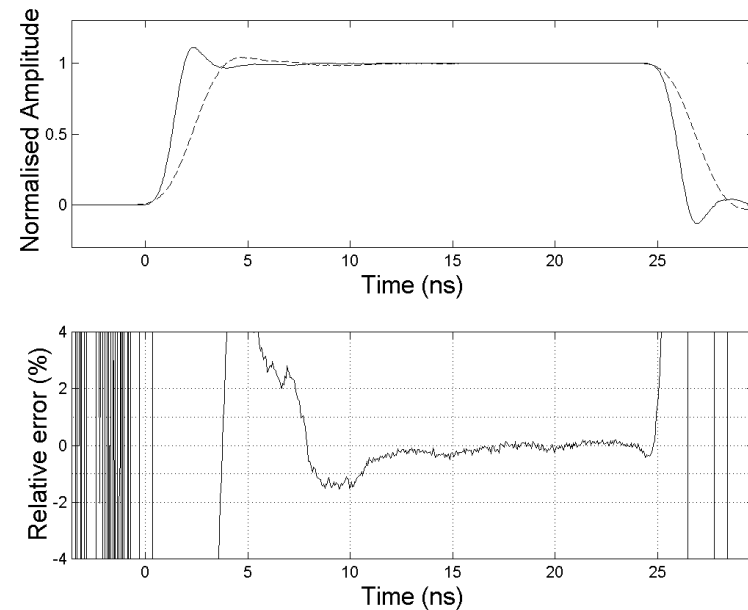
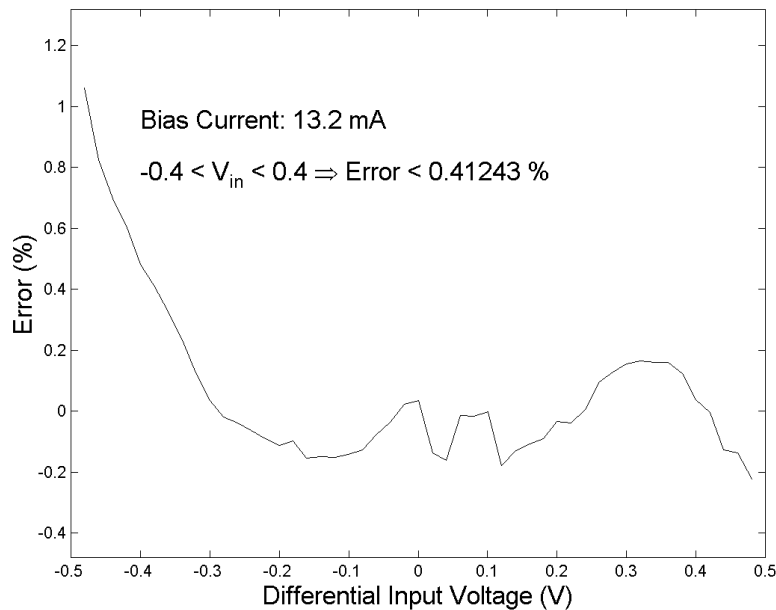
The linear laser-driver

- Transconductance linearisation:
 - Emitter degeneration resistors
- I_{bias} : programmable through the I²C interface
 - I_{bias} : 4.5 to 28mA in steps of 0.8mA

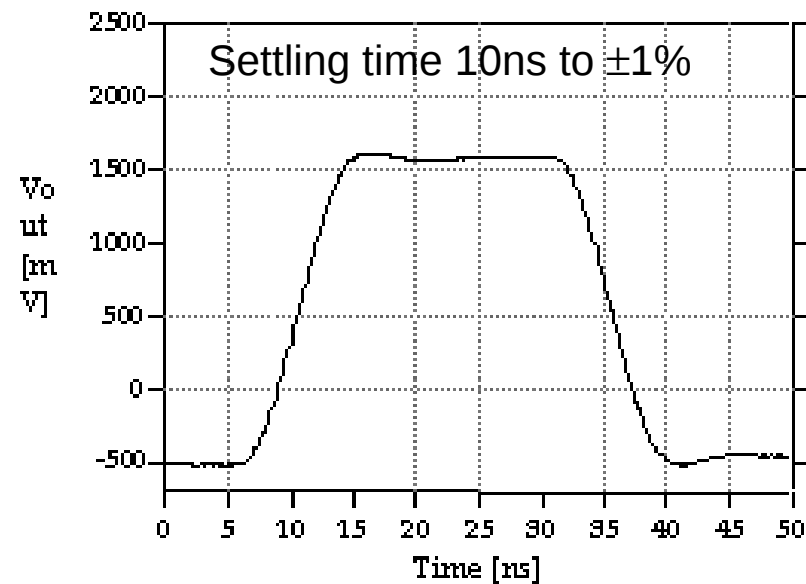
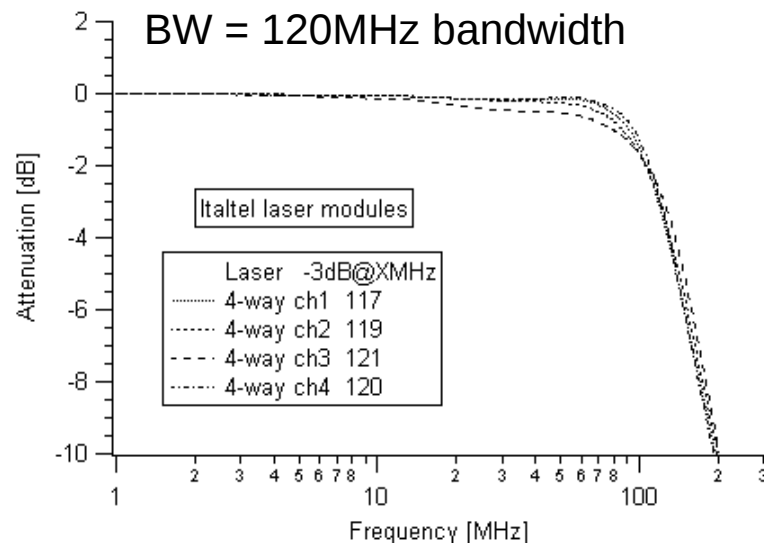
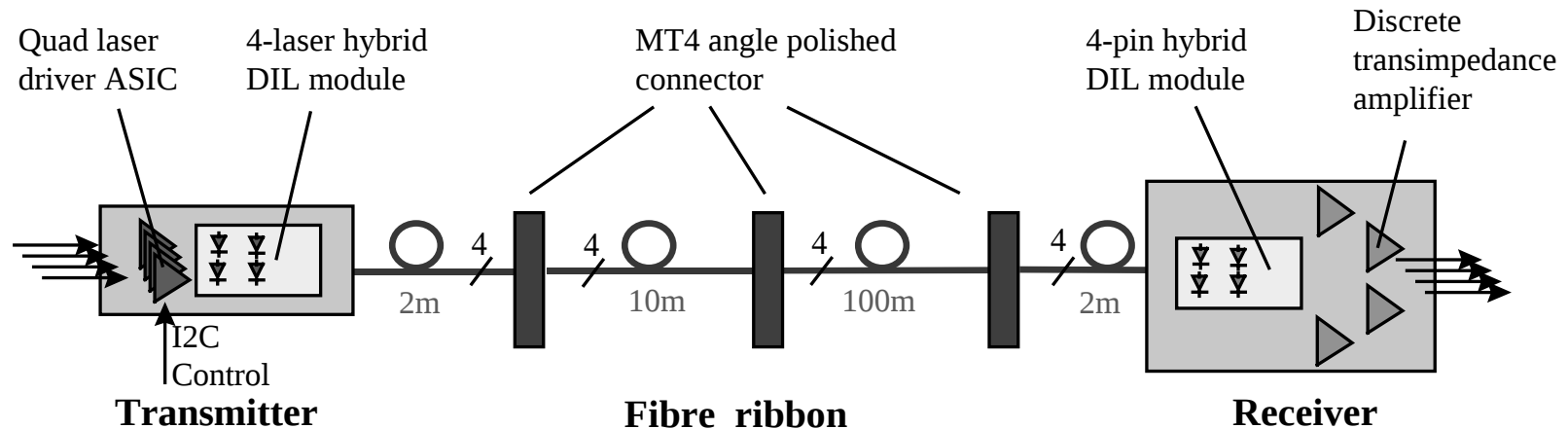


The linear laser-driver

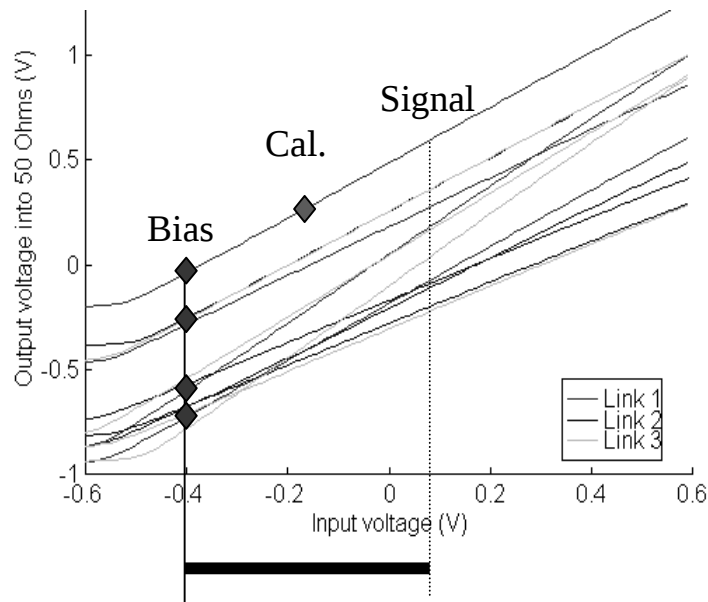
- Modulation current: 5mA for $|V_{in}| \leq 400$ mV
- Integral nonlinearity:
 - Electrical: $< 0.14\%$
 - “Optical”: $< 0.42\%$
- APV-Mux out: ≈ 5 ns rise/fall
 - Settling time: < 11 ns to 1%
 - Crosstalk: $< 0.27\%$



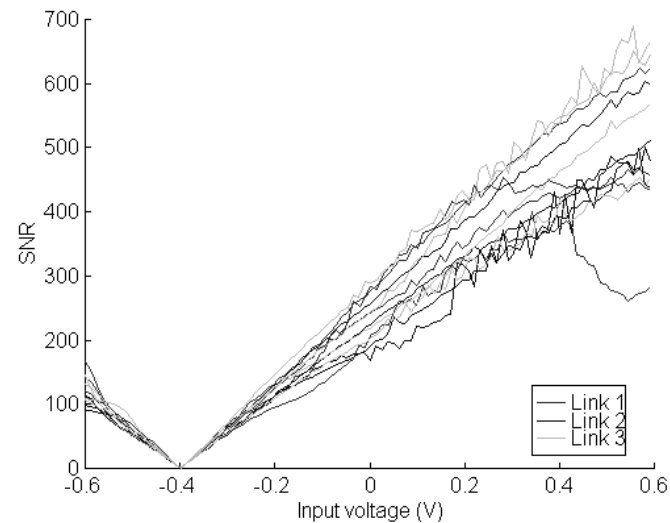
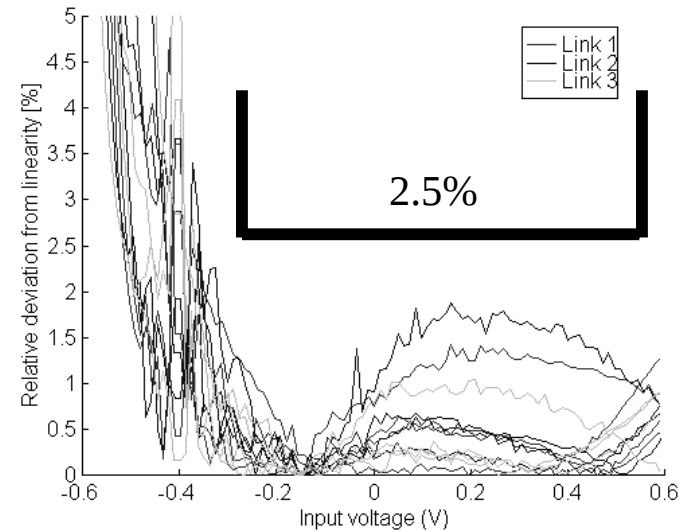
Optical link prototype



Optical link prototype



- Bias point : -400mV
- Calibration point : -150mV
- Input signal : 0 to 800mV



Optical link prototype

	Specified			Measured			
<i>characteristic</i>	<i>min</i>	<i>typ</i>	<i>max</i>				<i>unit</i>
Length	60	100	120	114			m
Gain (into 50 Ω)	0.7	1.43	2.85	0.98	1.2	1.7	V/V
Peak SNR		48		>50.9			dB
Relative linearity deviation		2.5		<2.5			%
Bandwidth		70		120			MHz
Settling time to 1%		18		<10			ns
Crosstalk at $t_s \geq 20\text{ns}$		-48		<55			dB